

Math 1553 Sample Midterm 2, Fall 2024

Name		GT ID	
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Circle your instructor and lecture below. Be sure to circle the correct choice!

Jankowski (A, 8:25-9:15) Wessels(B, 8:25-9:15) Hozumi (C, 9:30-10:20)

Wessels (D, 9:30-10:20) Kim (G, 12:30-1:20) Short (H, 12:30-1:20)

Shubin (I, 2:00-2:50) He (L, 3:30-4:20) Wan (M, 3:30-4:20)

Shubin (N, 5:00-5:50) Denton (W, 8:25-9:15)

Please read the following instructions carefully.

- Write your initials at the top of each page.
- The maximum score on this exam is 70 points, and you have 75 minutes to complete this exam. Each problem is worth 10 points.
- There are no calculators or aids of any kind (notes, text, etc.) allowed.
- As always, RREF means “reduced row echelon form.”
- The “zero vector” in \mathbf{R}^n is the vector in \mathbf{R}^n whose entries are all zero.
- On free response problems, show your work, unless instructed otherwise. A correct answer without appropriate work may receive little or no credit!
- We will hand out loose scrap paper, but it **will not be graded** under any circumstances. All answers and work must be written on the exam itself, with no exceptions.
- This exam is double-sided. You should have more than enough space to do every problem on the exam, but if you need extra space, you may use the *back side of the very last page of the exam*. If you do this, you must clearly indicate it.
- You may cite any theorem proved in class or in the sections we covered in the text.
- For questions with bubbles to fill in, you must fill them in the correct bubbles clearly and completely or you will not receive credit.

This is a practice exam. It was compiled by modifying one or two past midterms. It is meant to be similar in format, length, and difficulty to the real exam. It is **not** meant as a comprehensive list of study problems. We recommend completing the practice exam in 75 minutes, without notes or distractions.

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1. TRUE or FALSE. If the statement is *ever* false, circle FALSE. You do not need to show any work, and there is no partial credit. Each question is worth 2 points.

(a) Suppose v_1, v_2 , and b are vectors in \mathbf{R}^n and the equation

$$x_1v_1 + x_2v_2 = b$$

has exactly one solution. Then $\{v_1, v_2, b\}$ must be linearly independent.

True

False

(b) Let V be the set of all vectors $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$ in \mathbf{R}^3 of the form

$$x - 3y + z = 2.$$

Then V is a subspace of \mathbf{R}^3 .

True

False

(c) If a vector x is in the null space of a matrix A , then $4x$ is also in the null space of A .

True

False

(d) If A is a 7×4 matrix, then the matrix transformation $T(x) = Ax$ cannot be onto.

True

False

(e) If A is a 4×3 matrix and the equation $Ax = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}$ has exactly one solution,

then the transformation $T(x) = Ax$ must be one-to-one.

True

False

2. Multiple choice and short answer. You do not need to show work or justify your answers. Parts (a), (b), and (c) are unrelated.

(a) (3 points) Suppose v_1, v_2, v_3 , and v_4 are vectors in \mathbf{R}^4 . Which of the following must be true? Clearly circle all that apply.

If $\text{Span}\{v_1, v_2, v_3, v_4\} = \mathbf{R}^4$, then the set $\{v_1, v_2, v_3, v_4\}$ is linearly independent.

Suppose that the matrix A with columns v_1 through v_4 has one pivot, and let T be the matrix transformation $T(x) = Ax$. Then the range of T is a line.

If $v_1 - v_2 - v_3 + v_4 = 0$, then $\{v_1, v_2, v_3, v_4\}$ is linearly dependent.

(b) (4 points) Let $V = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \text{ in } \mathbf{R}^2 : y \leq 3x \right\}$.

Answer each of the following questions.

(i) Does V contain the zero vector? YES NO

(ii) Is V closed under addition? In other words, if u and v are in V , must it be true that $u + v$ is in V ? YES NO

(iii) Is V closed under scalar multiplication? In other words, if c is a real number and u is in V , must it be true that cu is in V ? YES NO

(iv) Is V a subspace of \mathbf{R}^2 ? YES NO

(c) (3 pts) Let A be a 15×7 matrix. If $\text{rank}(A) \leq 3$, which of the following are possible values for $\text{nullity}(A)$? Clearly select all that apply.

1

3

4

6

7

9

3. Short answer. Parts (a) through (d) are unrelated. There is no work necessary on this problem.

(a) This part is worth 4 points total.

(i) Let $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be the linear transformation for **counterclockwise** rotation by 13° . Find the standard matrix A for the transformation T .

$A = \begin{pmatrix} \cos(13^\circ) & -\sin(13^\circ) \\ \sin(13^\circ) & \cos(13^\circ) \end{pmatrix}$

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(ii) Write a specific matrix B satisfying $B \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -10 \\ 2 \end{pmatrix}$. Is this the only matrix satisfying $B \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -10 \\ 2 \end{pmatrix}$?

(b) (3 points) Let A be an $m \times n$ matrix, and let T be the associated linear transformation $T(x) = Ax$. Which of the following statements are true? Clearly circle all that apply.

If the columns of A are linearly independent, then $\dim(\text{range}(T)) = n$.

If the columns of A are linearly dependent, then T is onto.

If T is onto, then $\text{Col}(A) = \mathbf{R}^m$.

(c) (3 points) Determine which of the following statements are true.

If A is an $m \times n$ matrix, then there is a matrix C so that $A + C = 0$.

If A is a 3×7 matrix and B is a 4×3 matrix, then the matrix transformation T given by $T(x) = BAx$ has domain \mathbf{R}^4 and codomain \mathbf{R}^7 .

If A is an $n \times n$ matrix and $A^2 = 0$, then $(I - A)(I + A) = I$.

(d) (2 points) Let $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be the linear transformation that first rotates vectors by 90 degrees clockwise, then reflects across the line $y = -x$. Find $T \begin{pmatrix} 0 \\ 2 \end{pmatrix}$.

Clearly circle your answer below.

$\begin{pmatrix} 0 \\ 2 \end{pmatrix}$

$\begin{pmatrix} 0 \\ -2 \end{pmatrix}$

$\begin{pmatrix} 2 \\ 0 \end{pmatrix}$

$\begin{pmatrix} -2 \\ 0 \end{pmatrix}$

$\begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

4. You do not need to show your work on this problem. Parts (a), (b), (c), and (d) are unrelated.

(a) (3 points) Suppose that A is a matrix that represents a linear transformation T from \mathbf{R}^7 to \mathbf{R}^9 . In other words, T is the transformation given by the formula $T(x) = Ax$.

(i) How many rows does the matrix A have? Enter your answer here: _____.

(ii) Suppose the reduced row echelon form of the matrix A contains 3 pivots. Apply the Rank Theorem to A to fill in the following blanks with numbers.

$$\dim(\text{Col } A) = \underline{\hspace{2cm}} \qquad \dim(\text{Nul } A) = \underline{\hspace{2cm}}.$$

(b) (2 points) Suppose $T : \mathbf{R}^n \rightarrow \mathbf{R}^m$ is a transformation. Which **one** of the following is a definition that T is one-to-one?

For each x in \mathbf{R}^n , there is a vector y in \mathbf{R}^m so that $T(x) = y$.

For each x in \mathbf{R}^n , there is at most one vector y in \mathbf{R}^m so that $T(x) = y$.

For each y in \mathbf{R}^m , there is at most one vector x in \mathbf{R}^n so that $T(x) = y$.

(c) (3 points) Let V be the subspace of \mathbf{R}^4 consisting of all vectors of the form

$$\begin{pmatrix} -4x_4 \\ x_2 \\ x_2 + 6x_4 \\ x_4 \end{pmatrix}.$$

Write a basis for V .

(d) (2 points) Which of the following linear transformations are one-to-one? Clearly circle all that apply.

$T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ that rotates vectors counterclockwise by 15° .

$T : \mathbf{R}^3 \rightarrow \mathbf{R}^3$ given by $T(x) = \begin{pmatrix} 1 & 2 & 2 \\ 1 & 2 & 2 \\ 0 & 0 & 1 \end{pmatrix} x$.

5. Free response. Show your work unless otherwise indicated! A correct answer without sufficient work may receive little or no credit. For this problem, consider the matrix A and its reduced row echelon form given below.

$$A = \begin{pmatrix} 1 & 7 & 0 & -4 \\ -1 & -7 & 1 & 7 \\ 2 & 14 & 1 & -5 \end{pmatrix} \xrightarrow{RREF} \begin{pmatrix} 1 & 7 & 0 & -4 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

- (a) (2 points) Write a basis for $\text{Col } A$. Briefly justify your answer.
- (b) (4 points) Find a basis for $\text{Nul } A$.
- (c) (2 points) Write one vector x that is not the zero vector and is in the null space of A . Briefly justify your answer.
- (d) (2 points) Let T be the matrix transformation $T(x) = Ax$. Circle the correct answers below. You do not need to show your work on this part.
- (i) The range of T is:
- a point a line a plane all of \mathbf{R}^3 all of \mathbf{R}^4
- (ii) The range of T is a subspace of:
- \mathbf{R} \mathbf{R}^2 \mathbf{R}^3 \mathbf{R}^4

6. Free response. Show your work unless otherwise indicated! A correct answer without sufficient work may receive little or no credit.

Let $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be the linear transformation of rotation by 90° counterclockwise.

Let $U : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be the linear transformation that reflects vectors across the line $y = x$.

Let $V : \mathbf{R}^3 \rightarrow \mathbf{R}^2$ be the linear transformation

$$V(x_1, x_2, x_3) = (x_1 - 5x_2, 3x_1 - 4x_3).$$

- (a) (2 points) Write the standard matrix A for T .
(do *not* leave your answer in terms of sine and cosine; simplify it completely)

- (b) (2 points) Write the standard matrix B for U .

- (c) (3 points) Find the standard matrix C for V .

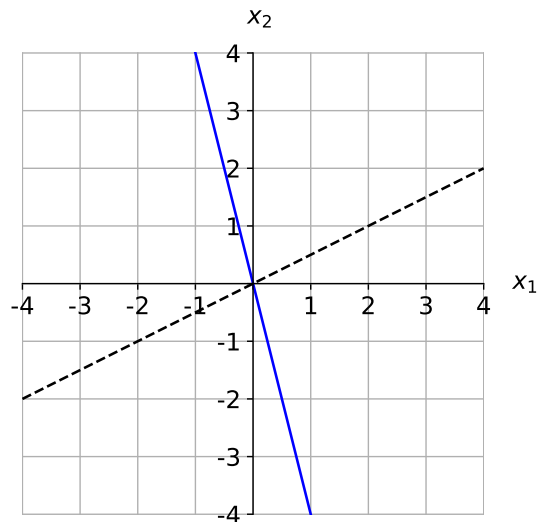
- (d) (3 points) Find the standard matrix D for the transformation $W : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ that first reflects vectors in \mathbf{R}^2 across the line $y = x$, then rotates vectors by 90° counterclockwise.

7. Free response. Show your work unless otherwise indicated! A correct answer without sufficient work may receive little or no credit. Parts (a), (b), and (c) are unrelated.

(a) (4 points) Let $A = \begin{pmatrix} 4 & a \\ -1 & b \end{pmatrix}$.

Find all values of a and b so that $A^2 = A$.

(b) (4 points) Write a single matrix A with the property that $\text{Col}(A)$ is the solid line graphed below and $\text{Nul}(A)$ is the dotted line graphed below.



(c) (2 points) Give one specific example of a subspace V of \mathbf{R}^3 that contains the vector $\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$. Briefly justify your answer.

This page is reserved **ONLY** for work that did not fit elsewhere on the exam.

If you use this page, please clearly indicate (on the problem's page and here) which problems you are doing.