1. Let \( A = \begin{pmatrix} 7 & 1 & 4 & 1 \\ -1 & 0 & 0 & 6 \\ 9 & 0 & 2 & 3 \\ 0 & 0 & 0 & -1 \end{pmatrix} \)

   a) Compute \( \det(A) \).

   b) Compute \( \det(A^{-1}) \) without doing any more work.

   c) Compute \( \det((A^T)^5) \) without doing any more work.

   d) Find the volume of the parallelepiped formed by the columns of \( A \).

Solution.

   a) The second column has three zeros, so we expand by cofactors:

   \[
   \det \begin{pmatrix} 7 & 1 & 4 & 1 \\ -1 & 0 & 0 & 6 \\ 9 & 0 & 2 & 3 \\ 0 & 0 & 0 & -1 \end{pmatrix} = -\det \begin{pmatrix} -1 & 0 & 6 \\ 9 & 2 & 3 \\ 0 & 0 & -1 \end{pmatrix}
   \]

   Now we expand the second column by cofactors again:

   \[
   \cdots = -2 \det \begin{pmatrix} -1 & 6 \\ 0 & -1 \end{pmatrix} = (-2)(-1)(-1) = -2.
   \]

   b) From our notes, we know \( \det(A^{-1}) = \frac{1}{\det(A)} = -\frac{1}{2} \).

   c) \( \det(A^T) = \det(A) = -2 \). By the multiplicative property of determinants, if \( B \) is any \( n \times n \) matrix, then \( \det(B^n) = (\det(B))^n \), so

   \[
   \det((A^T)^5) = (\det A^T)^5 = (-2)^5 = -32.
   \]

   d) Volume of the parallelepiped is \( |\det(A)| = 2 \).

2. Play matrix tic-tac-toe!

   Instead of X against O, we have 1 against 0. The 1-player wins if the final matrix has nonzero determinant, while the 0-player wins if the determinant is zero. You can change who goes first, and you can also modify the size of the matrix.

   Click the link above, or copy and paste the url below:

   http://textbooks.math.gatech.edu/ila/demos/tictactoe/tictactoe.html

   Can you think of a winning strategy for the 0 player who goes first in the \( 2 \times 2 \) case?

   Is there a winning strategy for the 1 player if they go first in the \( 2 \times 2 \) case?

3. Let \( A \) be an \( n \times n \) matrix.

   a) If \( \det(A) = 1 \) and \( c \) is a scalar, what is \( \det(cA) \)?
b) Using cofactor expansion, explain why \( \det(A) = 0 \) if \( A \) has adjacent identical columns.

Solution.

a) By the properties of the determinant, scaling one row by \( c \) multiplies the determinant by \( c \). When we take \( cA \) for an \( n \times n \) matrix \( A \), we are multiplying each row by \( c \). This multiplies the determinant by \( c \) a total of \( n \) times. Thus, if \( A \) is \( n \times n \) and \( \det(A) = 1 \), then
\[
\det(cA) = c^n \det(A) = c^n (1) = c^n.
\]

b) If \( A \) has identical adjacent columns, then the cofactor expansions will be identical, except the signs of the cofactors will be opposite (due to the \((-1)^n\) power factors).
   Therefore, \( \det(A) = -\det(A) \), so \( \det A = 0 \).

4. Is there a \( 3 \times 3 \) matrix \( A \) with only real entries, such that \( A^6 = -I \)? Either write such an \( A \), or show that no such \( A \) exists.

Solution.

No. If \( A^6 = -I \) then
\[
[\det(A)]^6 = \det(A^6) = \det(-I) = (-1)^3 = -1.
\]
In other words, if \( A^6 = -I \) then \([\det(A)]^6 = -1\), which is impossible since \( \det(A) \) is a real number.

Similarly, \( A^6 = -I \) is impossible if \( A \) is \( 5 \times 5 \), \( 7 \times 7 \), etc.

Note that if \( A \) is \( 2 \times 2 \), then it is possible to get \( A^6 = -I \). Just take \( A \) to be the matrix of counterclockwise rotation by \( \frac{\pi}{6} \) radians.
5. In this problem, you need not explain your answers; just circle the correct one(s).

Let $A$ be an $n \times n$ matrix.

a) Which one of the following statements is correct?

1. An eigenvector of $A$ is a vector $v$ such that $Av = \lambda v$ for a nonzero scalar $\lambda$.

2. An eigenvector of $A$ is a nonzero vector $v$ such that $Av = \lambda v$ for a scalar $\lambda$.

3. An eigenvector of $A$ is a nonzero scalar $\lambda$ such that $Av = \lambda v$ for some vector $v$.

4. An eigenvector of $A$ is a nonzero vector $v$ such that $Av = \lambda v$ for a nonzero scalar $\lambda$.

b) Which one of the following statements is not correct?

1. An eigenvalue of $A$ is a scalar $\lambda$ such that $A - \lambda I$ is not invertible.

2. An eigenvalue of $A$ is a scalar $\lambda$ such that $(A - \lambda I)v = 0$ has a solution.

3. An eigenvalue of $A$ is a scalar $\lambda$ such that $Av = \lambda v$ for a nonzero vector $v$.

4. An eigenvalue of $A$ is a scalar $\lambda$ such that $\det(A - \lambda I) = 0$.

Solution.

a) Statement 2 is correct: an eigenvector must be nonzero, but its eigenvalue may be zero.

b) Statement 2 is incorrect: the solution $v$ must be nontrivial.

6. True or false: If $v_1$ and $v_2$ are linearly independent eigenvectors of an $n \times n$ matrix $A$, then they must correspond to different eigenvalues.

Solution.

False. For example, if $A = I_2$ then $e_1$ and $e_2$ are linearly independent eigenvectors both corresponding to the eigenvalue $\lambda = 1$.

7. In what follows, $T$ is a linear transformation with matrix $A$. Find the eigenvectors and eigenvalues of $A$ without doing any matrix calculations. (Draw a picture!)

a) $T$ = projection onto the $xz$-plane in $\mathbb{R}^3$.

b) $T$ = reflection over $y = 2x$ in $\mathbb{R}^2$. 
Solution.

a) Here is a picture you can play with [https://www.geogebra.org/calculator/sxhzwmxy](https://www.geogebra.org/calculator/sxhzwmxy)

\[ T(x, y, z) = (x, 0, z), \text{ so } T \text{ fixes every vector in the }xz\text{-plane and destroys every vector of the form } (0, a, 0) \text{ with } a \text{ real. Therefore, } \lambda = 1 \text{ and } \lambda = 0 \text{ are eigenvalues and in fact they are the only eigenvalues since their combined eigenvectors span all of } \mathbb{R}^3. \]

The eigenvectors for \( \lambda = 1 \) are all vectors of the form \( \begin{pmatrix} x \\ 0 \\ z \end{pmatrix} \) where at least one of \( x \) and \( z \) is nonzero, and the eigenvectors for \( \lambda = 0 \) are all vectors of the form \( \begin{pmatrix} 0 \\ y \\ 0 \end{pmatrix} \) where \( y \neq 0 \). In other words:

The 1-eigenspace consists of all vectors in \( \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \), while the 0-eigenspace consists of all vectors in \( \text{Span} \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \)

b) Here is the picture you can play with [https://www.geogebra.org/calculator/xxmhzgev](https://www.geogebra.org/calculator/xxmhzgev)
$T$ fixes every vector along the line $y = 2x$, so $\lambda = 1$ is an eigenvalue and its eigenvectors are all vectors \( \begin{pmatrix} t \\ 2t \end{pmatrix} \) where $t \neq 0$.

$T$ flips every vector along the line perpendicular to $y = 2x$, which is $y = -\frac{1}{2}x$ (for example, $T(-2, 1) = (2, -1)$). Therefore, $\lambda = -1$ is an eigenvalue and its eigenvectors are all vectors of the form \( \begin{pmatrix} s \\ -\frac{1}{2}s \end{pmatrix} \) where $s \neq 0$. 